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END OF SEARCH HISTORY

Key: IEEE JNL = IEEE Journal or Magazine, IEE JNL = IEE Journal or Magazine, IEEE CNF = IEEE Conference, IEE CNF = IEE Conference, IEEE STD = IEEE Standard

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6. **A multi-robot approach to stealthy navigation in the presence of an observer**
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7. **Exploiting task regularities to transform between reference frames in robot teams**
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- 8. Method and system for robot end effector path correction using 3-D ultrasound sensors**
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Volume 2, 28 June-2 July 2000 Page(s):1240 - 1243 vol.2
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- 9. Sea trials of AUV "R-One Robot" equipped with a closed cycle diesel engine system**
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- 10. Programming complex robot tasks by prediction: experimental results**
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- 11. Planning mobile sensor net deployment for navigationally-challenged sensor nodes**
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